

... , ... , ... , ... , ... , ...

1.

K_{mpt}

$$k_{ii} = D(\sigma_{mpt}^{(i)}), \quad (1)$$

$$k_{ii'} = 0.$$

$$r_{ii}^{mpt} = 1.$$

2.

$$R_{mpt} = \begin{pmatrix} r_{11}^{mpt} & \dots & r_{1i}^{mpt} & \dots & r_{1\rho}^{mpt} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ r_{i1}^{mpt} & \dots & r_{ii}^{mpt} & \dots & r_{i\rho}^{mpt} \\ \vdots & \vdots & \vdots & \vdots & \vdots \\ r_{\rho 1}^{mpt} & \dots & r_{\rho i}^{mpt} & \dots & r_{\rho\rho}^{mpt} \end{pmatrix}, \quad (2)$$

1,

$\sigma_{mpt}^{(i)}$

() [1]

r_{ii}^{mpt} [2].

0.

1.

$$M_{\rho}$$

	$\sigma_{mpt}^{(1)}$	$\sigma_{mpt}^{(2)}$...	$\sigma_{mpt}^{(i)}$...	$\sigma_{mpt}^{(\rho)}$
$\sigma_{mpt}^{(1)}$	r_{11}^{mpt}	r_{12}^{mpt}	...	r_{1i}^{mpt}	...	$r_{1\rho}^{mpt}$
$\sigma_{mpt}^{(2)}$	r_{21}^{mpt}	r_{22}^{mpt}	...	r_{2i}^{mpt}	...	$r_{2\rho}^{mpt}$
\vdots	\vdots	\vdots	\vdots	\vdots	\vdots	\vdots
$\sigma_{mpt}^{(i)}$	r_{i1}^{mpt}	r_{i2}^{mpt}	...	r_{ii}^{mpt}	...	$r_{i\rho}^{mpt}$
\vdots	\vdots	\vdots	\vdots	\vdots	\vdots	\vdots
$\sigma_{mpt}^{(\rho)}$	$r_{\rho 1}^{mpt}$	$r_{\rho 2}^{mpt}$...	$r_{\rho i}^{mpt}$...	$r_{\rho\rho}^{mpt}$

$\sigma^{(1)}, \dots, \sigma^{(i)}, \dots, \sigma^{(\rho)}$ СИЛЬНО

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0.

[2].

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[3]

3.

I.

2.

2. S_{mpt}

3.

$$S_{mpt} = (y_{mpt}^{(1)}, y_{mpt}^{(j)}, \dots, y_{mpt}^{(\rho')}, \overline{y_{mpt}})$$

$$Y = (Y^{(1)}, \dots, Y^{(j)}, \dots, Y^{(\rho')})$$

$$\sigma_{mpt}^{(i)} \quad - m,$$

$$- p,$$

$$y_{mpt}^{(1)} = f_1^{mpt}(\sigma_{mpt}^{(1)}, \dots, \sigma_{mpt}^{(i)}, \dots, \sigma_{mpt}^{(\rho)})$$

$$y_{mpt}^{(j)} = f_j^{mpt}(\sigma_{mpt}^{(1)}, \dots, \sigma_{mpt}^{(i)}, \dots, \sigma_{mpt}^{(\rho)}) \quad (3)$$

$$y_{mpt}^{(\rho')} = f_{\rho'}^{mpt}(\sigma_{mpt}^{(1)}, \dots, \sigma_{mpt}^{(i)}, \dots, \sigma_{mpt}^{(\rho)})$$

$$f_1^{mpt}, \dots, f_j^{mpt}, \dots, f_{\rho'}^{mpt}$$

$$Y_{mpt} = A^{mpt} [\sigma_{mpt}] \quad (4)$$

$$A^{mpt} = \{a_{ji}^{mpt}\} -$$

$$Y_{mpt}$$

$$y_{mpt}$$

$$\sigma_{mpt}^{(i)}$$

$$: y_{mpt}^{(j)} = \sigma_{mpt}^{(j)}$$

$$(y_{mpt}^{(1)}, \dots, y_{mpt}^{(j)}, \dots, y_{mpt}^{(\rho)}) = \overline{Y}_{mpt}$$

$$(3) \tag{4}$$

$$y_{mpt}^{(1)} = \sum_{i=1}^{\rho} a_{1i}^{mpt} \sigma_{mpt}^{(i)}$$

$$y_{mpt}^{(j)} = \sum_{i=1}^{\rho} a_{ji}^{mpt} \sigma_{mpt}^{(i)} \tag{5}$$

$$y_{mpt}^{(\rho)} = \sum_{i=1}^{\rho} a_{\rho i}^{mpt} \sigma_{mpt}^{(i)}$$

$$a_{1i}, \dots, a_{ji}, \dots, a_{\rho i}$$

системы координат или факторные нагрузки
 $Y^{(1)}, \dots, Y^{(j)}, \dots, Y^{(\rho)}$,

$$A_{mpt} = \{a_{ji}^{mpt}\} \tag{6}$$

$$A_{mpt} = \begin{pmatrix} a_{11}^{mpt} & a_{12}^{mpt} & \dots & a_{1i}^{mpt} & \dots & a_{1\rho}^{mpt} \\ a_{21}^{mpt} & a_{22}^{mpt} & \dots & a_{2i}^{mpt} & \dots & a_{2\rho}^{mpt} \\ \dots & \dots & \dots & \dots & \dots & \dots \\ a_{j1}^{mpt} & a_{j2}^{mpt} & \dots & a_{ji}^{mpt} & \dots & a_{j\rho}^{mpt} \\ \dots & \dots & \dots & \dots & \dots & \dots \\ a_{\rho 1}^{mpt} & a_{\rho 2}^{mpt} & \dots & a_{\rho i}^{mpt} & \dots & a_{\rho \rho}^{mpt} \end{pmatrix} \tag{7}$$

$$A_{mpt}^T = \begin{pmatrix} a_{11}^{mpt} & a_{12}^{mpt} & \dots & a_{j1}^{mpt} & \dots & a_{\rho 1}^{mpt} \\ a_{21}^{mpt} & a_{22}^{mpt} & \dots & a_{j2}^{mpt} & \dots & a_{\rho 2}^{mpt} \\ \dots & \dots & \dots & \dots & \dots & \dots \\ a_{i1}^{mpt} & a_{i2}^{mpt} & \dots & a_{ji}^{mpt} & \dots & a_{\rho i}^{mpt} \\ \dots & \dots & \dots & \dots & \dots & \dots \\ a_{\rho 1}^{mpt} & a_{\rho 2}^{mpt} & \dots & a_{j\rho}^{mpt} & \dots & a_{\rho \rho}^{mpt} \end{pmatrix} \tag{8}$$

$y_{mpt}^{(1)}, \dots, y_{mpt}^{(j)}, \dots, y_{mpt}^{(p)}$

S_{mpt}

$\sigma^{(1)}, \dots, \sigma^{(i)}, \dots, \sigma^{(p)}$.

[4]:

1)

$$y_{mpt}^{(j)} = \sum_{i=1}^p a_{ji}^{mpt} \sigma_{mpt}^{(i)}, \quad (9)$$

где $j=1, \dots, p$.

$$\sum_{i=1}^p (a_{ji}^{mpt})^2 = 1; \quad (10)$$

2)

$$k_{hl} = \text{cov}(y_{mpt}^{(b)}, y_{mpt}^{(l)}) = 0, \quad b \neq l; \quad (11)$$

3)

$$D = \sum_{j=1}^{p'} D_j(y_{mpt}^{(j)}) = \sum_{i=1}^p D_i(\sigma_{mpt}^{(i)}), \quad (12)$$

$D_i(\sigma_{mpt}^{(i)})$
 $D_j(y_{mpt}^{(j)})$

$$\xi = \frac{1}{a_j} \sim D(y_{mpt}^{(j)}), \quad (13)$$

4)

$$D(y_{mpt}^{(1)}) \geq D(y_{mpt}^{(2)}) \geq \dots \geq D(y_{mpt}^{(\rho)}) \quad (14)$$

$$S_{mpt} \left(x - \frac{M_{pt}}{Y^{(1)}, \dots, Y^{(j)}, \dots, Y^{(\rho)}} \right)$$

$$\Sigma^{(1)}, \dots, \Sigma^{(j)}, \dots, \Sigma^{(\rho)}, \quad \sigma^{(1)}, \dots, \sigma^{(j)}, \dots, \sigma^{(\rho)}$$

$$S_{mpt} \left(1 - \frac{2}{\dots} \right)$$

$$\left(\dots \right) \quad [4].$$

o

4.

$$\sigma_{mpt}^{(i)} \quad y_{mpt}^{(j)}$$

$$\langle a_{j1}, a_{j2}, \dots, a_{ji}, \dots, a_{jp} \rangle = \bar{a}_j^{A_{mpt}} \quad (15)$$

$$\mu_j \quad \sigma_{mpt}^{(i)}$$

$$\bar{a}_j = \langle a_{j1}, a_{j2}, \dots, a_{ji}, \dots, a_{jp} \rangle^T \quad (16)$$

$$A_{mpt} = \begin{pmatrix} \bar{a}_1^T \\ \bar{a}_2^T \\ \vdots \\ \bar{a}_j^T \\ \vdots \\ \bar{a}_p^T \end{pmatrix} \quad (17)$$

$$\bar{a}_j^{A_{mpt}} = \langle a_{j1}, a_{j2}, \dots, a_{ji}, \dots, a_{jp} \rangle -$$

$$A_{mpt}^T = (\bar{a}_1, \bar{a}_2, \dots, \bar{a}_j, \dots, \bar{a}_p) \quad (18)$$

$$R_{mpt} \bar{a}_j = \bar{a}_j C_{mpt} \quad (19)$$

$$C_{mpt} = \begin{pmatrix} c_{11} & c_{12} & \dots & c_{1j} & \dots & c_{1p} \\ c_{21} & c_{22} & \dots & c_{2j} & \dots & c_{2p} \\ \dots & \dots & \dots & \dots & \dots & \dots \\ c_{j1} & c_{j2} & \dots & c_{jj} & \dots & c_{jp} \\ \dots & \dots & \dots & \dots & \dots & \dots \\ c_{p1} & c_{p2} & \dots & c_{pj} & \dots & c_{pp} \end{pmatrix} \quad (20)$$

$$\bar{a}_j^T = \bar{a}_j^{-1} \quad (21)$$

$$(19) \quad \bar{a}_j^T R_{mpt} \bar{a}_j = C_{mpt} \quad (22)$$

$$y_{mpt}^{(j)}$$

$$C_{mpt} = E, \quad (23)$$

$$C_{mpt} = E, \quad (15)$$

$$\vec{r}_{jj} = \vec{a}_j \cdot \vec{a}_j^T, \quad (24)$$

$$C_{mpt} = A_{mpt}^T R_{mpt} A_{mpt} \quad (25)$$

$$C_{mpt} = E = A_{mpt}^T R_{mpt} A_{mpt} \quad (26)$$

$$R_{mpt} = A_{mpt} A_{mpt}^T \quad (27)$$

$$r_{jl} = a_{j1}a_{l1} + a_{j2}a_{l2} + \dots + a_{jp}a_{lp}. \quad (28)$$

$$r_{il} = \frac{k_{il}}{\sqrt{k_{ii}k_{li}}}. \quad (29)$$

$$= \vec{a}_j^T K_{mpt} \vec{a}_j - \lambda (\vec{a}_j^T \vec{a}_j - \vec{a}_j \cdot \vec{a}_j). \quad (30)$$

$$\alpha_j \alpha_j = \text{const} -$$

$$\frac{\partial \varphi}{\partial \vec{a}_j} = K_{mpt} \vec{a}_j - \lambda \vec{a}_j = (K_{mpt} - \lambda E) \vec{a}_j = 0. \quad (31)$$

$$K_{mpt} \vec{a}_j = \lambda E \vec{a}_j. \quad (32)$$

$$= L = \begin{pmatrix} \lambda_1 & 0 & 0 & \dots & 0 & \dots & 0 \\ 0 & \lambda_2 & 0 & \dots & 0 & \dots & 0 \\ \dots & \dots & \dots & \dots & \dots & \dots & \dots \\ 0 & 0 & 0 & \dots & \lambda_j & \dots & 0 \\ \dots & \dots & \dots & \dots & \dots & \dots & \dots \\ 0 & 0 & 0 & \dots & 0 & \dots & \lambda_p \end{pmatrix}, \quad (33)$$

λ_j

K_{mpt}

$$(31). \quad (32)$$

$$K_{mpt} \vec{\alpha}_j = L \vec{\alpha}_j, \quad (34)$$

L :

$$\vec{\alpha}_j^{-1} K_{mpt} \vec{\alpha}_j = L. \quad (35)$$

A_{mpt}

K_{mpt}

$$A_{mpt}^T K_{mpt} A_{mpt} = L. \quad (36)$$

$\Sigma^{(1)}$

$Y^{(1)}$

$$A_{mpt}^T = A_{mpt}^{-1}. \quad (37)$$

$$L = A_{mpt}^{-1} K_{mpt} A_{mpt}. \quad (38)$$

$$K_{mpt} A_{mpt} = A_{mpt} L. \quad (39)$$

$$\vec{\alpha}_j^T K_{mpt} \vec{\alpha}_j = L. \quad (40)$$

(31):

$$K_{mpt} \vec{\alpha}_j - \lambda E \vec{\alpha}_j = 0. \quad (41)$$

$$(K_{mpt} - \lambda E) \vec{\alpha}_j = 0 \quad (42)$$

$$\text{Det} (K_{mpt} - \lambda E) = 0. \quad (43)$$

$$\lambda_j (j=1, \dots, p), \quad [5]. \quad \lambda_1 \geq \lambda_2 \geq \dots \geq \lambda_j \geq \dots \geq \lambda_p \geq 0.$$

, [6]

$$\sigma_{y_j}^2 = D(y^{(j)}) = \vec{\alpha}_j^T K_{mpt} \vec{\alpha}_j. \quad (44)$$

K_{mpt}

\bar{c}_j Cv_{mpt}

(44)

$$K_{mpt} \bar{c}_j = \bar{c}_j D(y^{(j)}). \quad (45)$$

 $D_j(y^{(j)})$ K_{mpt}

$$\text{Det}(K_{mpt} - D(y^{(j)})E) = 0. \quad (46)$$

 Cv_{mpt}

$$D(y^{(j)})_j = cv_{jj}. \quad (47)$$

 cv_{jj}
 $y^{(j)}$

$$cv_{jj} = \bar{a}_j^T K_{mpt} \bar{a}_j. \quad (48)$$

(45)

$$K_{mpt} \bar{a}_j - D(y^{(j)})_j \bar{a}_j = 0. \quad (49)$$

 α_{ji}

$$\bar{a}_j = (\alpha_{j1}^*, \dots, \alpha_{ji}^*, \dots, \alpha_{j\rho}^*), \quad (50)$$

 α_{ji}^*

$$\sum_{i=1}^{\rho} \alpha_{ji}^{*2} = D(y^{(j)}), \quad (51)$$

 $i = 1, \dots, \rho$ – номера исходных свойств,

1-

$$S_1 = \sum_{i=1}^{\rho} \alpha_{i1}^{*2} = \max, \quad (52)$$

 $k_{ji} = \alpha_{j1} \cdot \alpha_{i1}$

2-

 R_{mpt}

$$R_{mpt} \bar{a}_j = \mu E \bar{a}_j \quad (53)$$

$$\alpha_{ji}^* = \alpha_{ij}^*$$

$$A_{mpt} \quad A_{mpt}$$

$$a_{ji}^* = a_{ij}^*$$

$$a_{ji}^{*2} = \mu_j, \quad (65)$$

$$\alpha_{ji}^{*2} k_{ii} = D(y^{(j)})_j = \lambda_j. \quad (66)$$

(29)

$$\frac{\alpha_{ij}^{*2}}{\mu_j} = \frac{\alpha_{ij}^{*2}}{D(y^{(j)})_j} \sqrt{D(\sigma_{mpt}^{(i)})^2}, \quad (67)$$

$$D(\sigma_{mpt}^{(i)}) = k_{ii} = \sigma_{ii}^2 = D(\sigma_{mpt}^{(i)}) = k_{ii} = \sigma_{ii}^2 -$$

$$\sigma_{ii}^2 -$$

λ_j

m (

j -

c ,

[7],

$$D = \frac{\lambda_j}{m} = \frac{\mu_j}{n} = \frac{D(y^{(j)})}{\sum_{j=1}^p D(y^{(j)})}. \quad (68)$$

$n -$

μ_j .

$$\mu_j = \lambda_j \frac{m}{n}. \quad (69)$$

$$a_{ji}^{*2} = \lambda_j \frac{m}{n}. \quad (70)$$

$$a_{ji}^{*2} = \alpha_{ji}^{*2} k_{ii} \frac{m}{n} \quad (71)$$

$$a_{ji}^{*2} = \alpha_{ij}^{*2} D(\sigma^{(i)}) \frac{m}{n}, \quad (72)$$

$$a_{ji}^* = \alpha_{ji}^* \sqrt{D(\sigma^{(i)}) \frac{m}{n}} \quad (73)$$

a_{ji} .

$$\sum_{i=1}^p \alpha_{ji}^{*2} = D(y^{(j)}), \quad (74)$$

(73),

A_{mpt} :

$$a_{ji}^* = \frac{\alpha_{ji}^* \sqrt{\lambda_j}}{\sqrt{\alpha_{j1}^{*2} + \alpha_{j2}^{*2} + \dots + \alpha_{j0}^{*2}}} \sqrt{D(\sigma_{mpt}^{(i)})}, \quad (75)$$

$$\alpha_{ji}^* \quad \bar{\alpha}_j^*$$

$$\sum_{i=1}^p \alpha_{1i}^{*2} > \sum_{i=1}^p \alpha_{2i}^{*2} > \dots > \sum_{i=1}^p \alpha_{ji}^{*2} > \dots > \sum_{i=1}^p \alpha_{pi}^{*2}. \quad (76)$$

$$\overline{\sigma_{mpt}^{(i)}} = \frac{\sigma_{mpt}^{(i)} - \overline{\sigma_{mpt}^{(i)}}}{D(\sigma_{mpt}^{(i)})} \quad (77)$$

$$r_{ii} = k_{ii} \quad (78)$$

$$R_{mpt} = K_{mpt} \quad (79)$$

$$(22), (24) \quad = Cv_{mpt} - \mu(\bar{r}_{jj} - \bar{\zeta}). \quad (80)$$

$$\bar{\zeta} = \bar{\alpha}_j \bar{\alpha}_j.$$

$$A_{mpt}$$

$$a_{ji}^* = \frac{\alpha_{ji}^* \sqrt{\lambda_j}}{\sqrt{\alpha_{j1}^{*2} + \alpha_{j2}^{*2} + \dots + \alpha_{j0}^{*2}}} \quad (81)$$

$$y_{mpt}^{(i)} \quad (68).$$

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$$\lambda_j$$

1)

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[4]

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(81);

A_{mpt}

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$> \pm 0,5;$

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(68),

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